BASIC ELECTRICAL ENGINEERING

(Diploma 1ST SEM)



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Text Book:

- 1. ABC of Electrical Engineering by jain and jain (Dhanpat Rai publication)
- 2. Fundamental of Electrical and Electronics Engineering by B.L. Thereja
- 3. Fundamental of Electrical Engineering by J.B. Gupta.

CHAPTER-1

Concept of Current

The smallest known quantity of electric charge is the charge of an electron. So, all quantities of charge are expressed in multiples of this basic or fundamental unit i.e. charge of an electron. The SI unit of charge is coulomb (Symbol C) which is equal to charge of 6.24×10^{18} electrons.

The movement of electrons in a conductor remains unchannelised until it is acted upon by an electric field. The flow of electrons through a conductor constitutes an electric current & the path of electric current is known as electric circuit which is always a closed path. The direction of flow of positive

current is opposite to the direction of flow of electrons. So current can be defined as:

The time rate of flow of electric charge is current $I = \frac{d}{dt}$

The unit of current is "Ampere".

When a current is flowing in a conductor having non-uniform cross sectional area, the current is same for all Cross-Sections of the conductor in accordance to the principle of Conservation of charge.

- 1. Electric potential at a point is the work done in bringing a unit positive charge from infinity to that point.
- 2. It two points have different electric potentials, there is said to be a potential difference (p.d.) or voltage existing between the points.

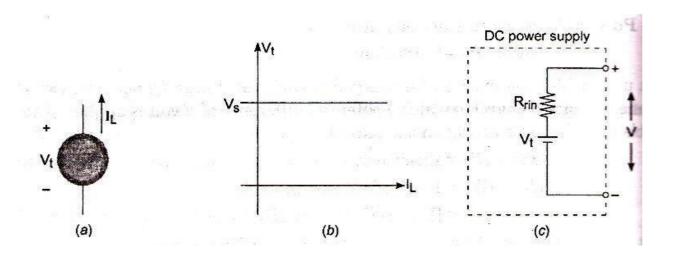
Concept of Source & Load

Voltage source

A Source may be a voltage or current source.

An ideal voltage source is a source that maintains the same voltage across its terminals irrespective of amount of current drawn from the source or whatever current flows into the source through its terminals (as shown in Fig.(a) below). Hence, the internal resistance of an ideal voltage source is zero. The voltage across the terminals is denoted as V_s . The current drawn from the source is denoted by I_L and the plot of terminal voltage against load current is shown in Fig.(b) below.

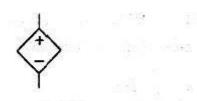
A Real/practical voltage source is represented by an ideal voltage source with a series resistance(r_{in}) with it as shown in Fig.(c) below.



(Figure (a) shows symbol of Ideal voltage source), (Figure (b) shows plot of V_t Vs I_L of an Ideal voltage source), Figure (c) shows a practical voltage source)

<u>Dependent and Independent voltage Source</u>

If the voltage across an ideal voltage source can be specified independently of any other variable in a circuit, it is called an INDEPENDENT voltage source. However, If the voltage across an ideal voltage source is determined by some other voltage or current in a circuit, it is called a DEPENDENT or CONTROLLED voltage source and it is represented in a circuit diagram as shown in Fig.(d) below.



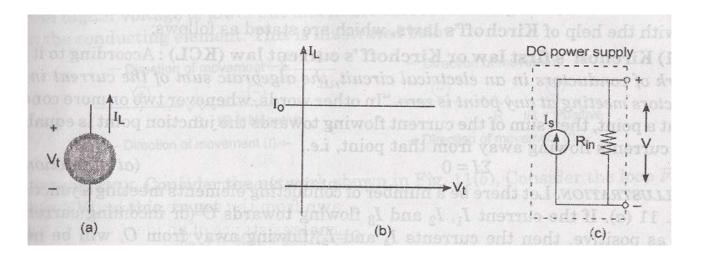
Controlled voltage source.

(Figure d)

Current source

An ideal current source is one in which there is no change in current irrespective of the voltage at which current is drawn of which the circuit symbol is shown in figure (a) below. The internal resistance of an ideal current source is infinity. A plot of current(I_L) drawn against terminal voltage is shown in Fig.(b) below where I₀ represents a constant current irrespective of change in terminal voltage.

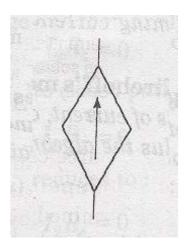
A Real/practical current source is represented by an ideal current source in parallel with a resistance(r_{in}) as shown in Figure (c) below.



(Figure (a) shows symbol of Ideal current source), (Figure (b) shows plot of I_L Vs V_t of an Ideal current source), Figure (c) shows a practical current source)

Dependent and Independent current Source

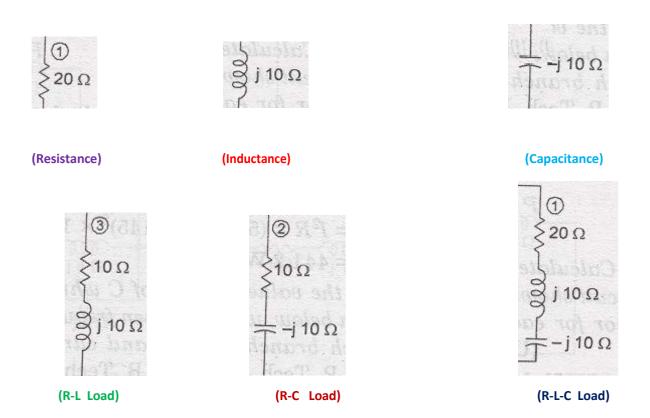
If the current through an ideal current source can be specified independently of any other variable in a circuit, it is called an INDEPENDENT current source. However, If the current through an ideal current source is determined by some other voltage or current in a circuit, it is called a DEPENDENT or CONTROLLED current source and is shown in Fig.(d) below.



(Controlled or Dependent Current Source)

LOAD

The electrical load is an application consuming electrical power and is represented by R(Resistance),L(Inductance),C(Capacitance),E(back EMF) etc. or combination of these circuit elements.



Ohms Law and Concept of Resistance

At a constant temperature ,the current passing between the two points of a conductor is directly proportional to the potential difference existing between the two points.

Mathematically, I $\propto V$ or V = IR(R is a constant of proportionality)

Electrical current in a conductor consists of movement of electrons. When electrons flow through a material they collide with other atomic particles and energy is lost in the form of heat due to these collisions and this is represented by resistance.

Resistance is the property of a material by virtue of which it opposes the flow of electrons (or current) through it. The opposition to flow of current is due to above collisions of electrons.

Resistance of a conductor(Figure(a) below) depends on its Length(L), Area of cross-section(A) and specific resistance or resistivity(ρ) of the material and is given by : R= ρ L/A

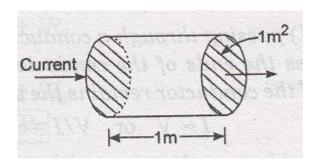


Figure (a)

[In the figure(a) above a conductor is shown with its length(L) = 1 metre & Area of cross- section(A) = $1m^2$]

Relation of V and I in series circuit

Conductors are said to be connected in series if they are connected end to end , one after another so that one end of the first conductor and one end of the last conductor are free and same current flows through all conductors and potential difference across each one is different depending upon their resistances. In figure S.1 below, A & D are free ends of three conductors AB, BC & CD connected in series and let $R_1, R_2 \& R_3$ be the respective resistances.

[Figure S.1] From the above figure,

Let, R = Resistance of the combination

V = Total potential difference across resistances. I =

Strength of Current

Then V=IR(1) But V=

sum of individual p.d. across R₁,R₂&R₃

So,

$$V = V_1 + V_2 + V_3 = IR_1 + IR_2 + IR_3$$
 (2) From

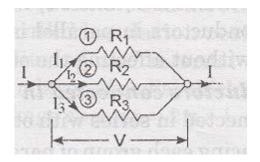
equation 1 & 2 we get $IR = IR_1 + IR_2 + IR_3$

Hence, R=IR₁+ R₂+ R₃

It follows from the above that if a number of conductors are connected in series then the combined resistance of the combination equals the sum of the individual resistances.

Relation of V and I in parallel circuit

Conductors are said to be connected in parallel if all of them are connected across two common points. In figure P.1 below three conductors of resistances R_1 , R_2 & R_3 are connected between the common points A & B. It will be observed that same potential difference exists between the ends of each conductor but the amount of current passing through each is different depending upon their resistances.



[Figure P.1]

Suppose the main current I is divided into I₁, I₂&I₃ through the resistors R₁,R₂&R₃ respectively. Let, R

= Resistance of the combination between A & B

V = potential difference I =

Strength of Current

Then,
$$I = \frac{V}{R}$$

By KCL, the main current entering this combination must come out as such & Hence,

$$| = |_1 + |_2 + |_3$$

Then
$$I = \frac{V}{R_1} + \frac{V}{R_2} = \frac{V}{R_3}$$
2P

From equations 1p & 2p we get

$$= \frac{V}{R} \frac{V}{R_1} + \frac{V}{R_2} \frac{V}{R_3}$$

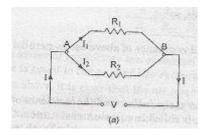
Hence,
$$\frac{1}{R} \frac{1}{R_1} + \frac{1}{R_2} + \frac{1}{R_2}$$

It follows from the above that if a number of conductors are connected in parallel then the reciprocal of combined resistance is equal to the sum of the reciprocals of individual resistances.

Division of Current in parallel circuit

Let us consider two resistors connected in parallel as shown in Figure P.2 below across a voltage V. Then, by ohm 's Law current in branches is

$$I_1 = \frac{V}{R_1} \& I_2 = \frac{V}{R_2}$$



Two resistors in parallel,

[Figure P.2]

Also considering the total current I & the total equivalent resistance of combination

i.e.
$$R = \frac{R_1 R_2}{R_1 + R_2}$$
 and $V = IR = I = \frac{R_1 R_2}{R_1 + R_2}$

from the above we get V=IR= I
$$\frac{R_1R_2}{R_1+R_2}$$
 IR_{2.....DCP1}

from equation DCP1 above we get
$$I_1 R_1 = I$$
 $\frac{R_1 R_2}{R_1 + R_2}$ o $I_2 R_2 = I$ $\frac{R_1 R_2}{R_1 + R_2}$

Thus,
$$I_1 = I$$
 $\frac{R_2}{R_1 + R_2}$ $I_2 = I$ $\frac{R_1}{R_1 + R_2}$

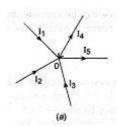
Hence, It is observed that in a parallel connected circuit of two resistances the current through a branch is the product of total current entering the combination & the Ratio of resistance of opposite side of the side through which the current is determined & the sum of individual resistances.

Kirchoff's current Law

According to Kirchoff's current Law "In any network of conductors in an electrical circuit, the algebraic sum of the current in all the conductors meeting at any point is zero".

i.e.
$$\Sigma I = 0$$

Let there be a number of conducting elements meeting at a junction 'o' as shown in figure(a) below.



If the currents $I_1,I_2\&I_3$ are flowing towards 'o'(incoming currents) be taken positive then the currents $I_4,\&I_5$ flowing away from o(outgoing currents0 be negative then

According to KCL,

$$I_1 + I_2 + I_3 - I_4 - I_5 = 0$$
 or $I_1 + I_2 + I_3 = I_4 + I_5$

This follows from the above that there can be no accumulation of charge at any point.

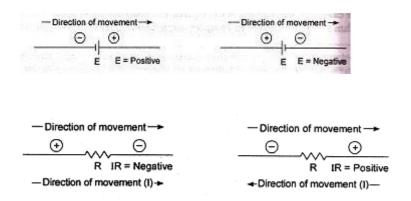
Sign Rules of KCL: If all the in-coming currents be taken to be positive then the outgoing currents must be taken Negative and vice versa.

Kirchoff's voltage Law

According to Kirchoff's voltage Law 'algebraic sum of the product of current & resistance of each conductor in any closed path(or mesh) in a network plus the algebraic sum of the emf's in that path is zero."

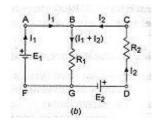
In other words
$$\Sigma IR + E = 0$$

Sign Rules of KVL: If we give positive sign to all rise in potential then we must give Negative sign for all fall in potential and vice versa as shown in Figure(a).



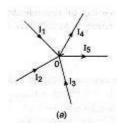
[Figure(a)]

Let us apply KVL to the circuit diagram in Figure(b) below and write down the Loop equations.



Considering the loop FABGF & applying KVL to this, we get

1. Find the values of I_3 assuming that $I_1 = 5A$, $I_2 = 2A$, $I_4 = 1A & I_5 = 4A$.



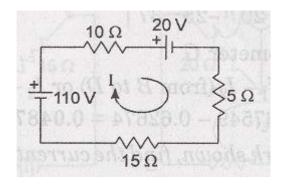
Solution: Application of KCL to node A in figure with proper sign convention results in the following equation:

$$I_1 + I_2 + I_3 - I_4 - I_5 = 0$$

Or Replacing the current values ,we find $I_3 = I_4$

$$+ I_5 - I_1 - I_2 = 1 + 4 - 5 - 2 = -2A(Ans)$$

2. Calculate the current flowing in the circuit and the potential difference(p.d) across the three resistances by applying KVL to the Network shown below.



Solution: Applying Kirchoff's voltage Law to the circuit shown above and assuming the current direction to be as shown let us move in the direction of current and write down the equations.

$$30I=0$$
; => I = 3 Amp.(Ans)

Potential difference across 10Ω resistance = $10I=10 \times 3 = 30$ volts (Ans) Potential

difference across 5Ω resistance = 5I=5 x 3 = 15 volts (Ans) Potential difference

across 15Ω resistance = $15I=15 \times 3 = 45$ volts (Ans)

There are two voltage sources i.e. 110 volt & 20 volt of which the first one(110 volt) is taken positive because , there is a rise in voltage from –ve terminal of battery to +ve terminal of battery as we move in clock-wise direction. Similarly for the second voltage source i.e.20 volt , there is a fall in voltage from +ve terminal of battery to –ve terminal of battery in the direction of movement. The voltage drops across 10Ω , 5Ω & 15Ω are –ve as they are all cases of fall in voltage in the direction of current flow.

DELTA-STAR TRANSFORMATION

This is a method of obtaining equivalent star of a delta connected circuit.

Consider a delta connected circuit with three resistances R₁₂, R₂₃ & R₃₁ as shown in figure S-D1 below.

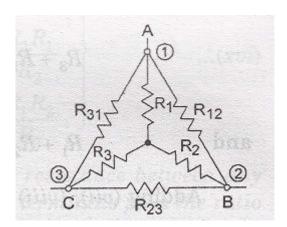


Fig.S-D1

Suppose its equivalent star circuit be represented by R_1 , R_2 & R_3 . The resistance between terminals A & B in delta connection

=
$$R_{12}x(R_{23}+R_{31})/(R_{12}+R_{23}+R_{31})$$
 (i) The resistance

between terminals A & B in star connection

=
$$R_1+R_2$$
(ii) Since the

terminals are same

$$R_1+R_2=[R_{12}x(R_{23}+R_{31})]/(R_{12}+R_{23}+R_{31})$$
(iii)

Similarly, by solving for terminals B & C, C & A we get

$$R_2+R_3=[R_{23}x(R_{31}+R_{12})]/(R_{12}+R_{23}+R_{31})$$
(iv)

&
$$R_3+R_1=[R_{31}x(R_{12}+R_{23})]/(R_{12}+R_{23}+R_{31})....(v)$$
 On solving

above equations we get the Delta – Star Transformation as :

$$R_1 = (R_{12}R_{31})/(R_{12} + R_{23} + R_{31})$$

$$R_2 = (R_{23}R_{12})/(R_{12} + R_{23} + R_{31})$$
(vi)

$$R_3 = (R_{31}R_{23})/(R_{12} + R_{23} + R_{31})$$

STAR- DELTA TRANSFORMATION

This is a method of obtaining equivalent delta of a given star connected circuit.

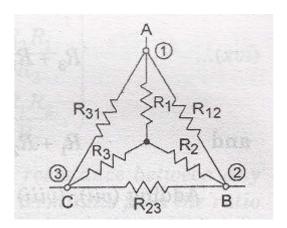


Figure. S-D2

Referring to the circuit with resistances connected in star i.e. R_1 , R_2 & R_3 as shown in figure S-D2 above and the equivalent DELTA values R_{12} , R_{23} & R_{31} can also be determined as follows:

Total resistance between B&C must be same for both star & delta connections. So,

Between terminals B & C :

$$R_2 + R_3 = R_{23}II (R_{31} + R_{12}) = (R_{23} R_{31} + R_{23} R_{12})/(R_{12} + R_{23} + R_{31})$$
(vii)

Similarly, For terminals C & A ,A&B we get,

$$R_3 + \ R_1 = R_{31} II \ (R_{12} + \ R_{23}) = (R_{31} \ R_{12} + \ R_{31} \ R_{23}) / (\ R_{12} + \ R_{23} + \ R_{31}) \(viii)$$

and
$$R_1 + R_2 = R_{12}II(R_{31} + R_{23}) = (R_{12}, R_{31} + R_{12}, R_{23})/(R_{12} + R_{23} + R_{31})$$
(ix)

Adding the above three equations we get:

$$2(R_1+R_2+R_3) = 2(R_{12}, R_{23}+R_{23}, R_{31}+R_{31}, R_{12})/(R_{12}+R_{23}+R_{31})$$

and
$$(R_1+R_2+R_3) = (R_{12}, R_{23}+R_{23}, R_{31}+R_{31}, R_{12})/(R_{12}+R_{23}+R_{31})$$
(x)

Solving the above equations for $R_1, R_2 \& R_3$ we get :

$$R_1 = R_{31}.R_{12}/(R_{12}+R_{23}+R_{31})$$
(xi)

$$R_2 = R_{12}.R_{23}/(R_{12}+R_{23}+R_{31})$$
(xii)

$$R_3 = R_{23}.R_{31}/(R_{12}+R_{23}+R_{31})$$
(xiii)

Dividing (xi) by (xii) we get,

$$R_1/R_2 = R_{31}/R_{23}$$
 OR $R_{31} = R_1$. R_{23}/R_2 (xiv)

Similarly we get

$$R_3/R_1 = R_{23}/R_{12}$$
 OR $R_{12} = R_1$. R_{23}/R_3 (xv)

Substituting the value of R_{31} & R_{12} from eqn.(xiv) & (xv) respectively in (vii) we get $R_2+R_3=$ {

$$R_{23}(R_{1.}R_{23}/R_{2}) + R_{23}(R_{1.}R_{23}/R_{3}) \} / \{ R_{23} + (R_{1.}R_{23}/R_{2}) + (R_{1.}R_{23}/R_{3}) \} R_{2} + R_{3} = \{ (R_{1.}R_{23}/R_{2}) + (R_{1.}R_{23}/R_{3}) \} / \{ 1 + (R_{1}/R_{2}) + (R_{1}/R_{3}) \}$$

$$R_2 + R_3 = (R_1.R_3.R_{23} + R_1.R_2.R_{23})/(R_2R_3 + R_1R_3 + R_1R_2) = R_1R_{23} (R_3 + R_2)/(R_2R_3 + R_1R_3 + R_1R_2)$$

$$R_1R_{23} = R_2R_3 + R_1R_3 + R_1R_2$$

OR
$$R_{23} = R_2 + R_3 + R_2 R_3 / R_1$$

Similarly we get

$$R_{31} = R_3 + R_1 + R_3 R_1 / R_2$$
 and $R_{12} = R_1 + R_2 + R_1 R_2 / R_3$

Hence, the Delta equivalent values are obtained given the star values of the network.

ELECTRO-MAGNETICINDUCTION

In 1931, M. Faraday discovered that a current is generated whenever the magnetic flux linked with a circuit changes.

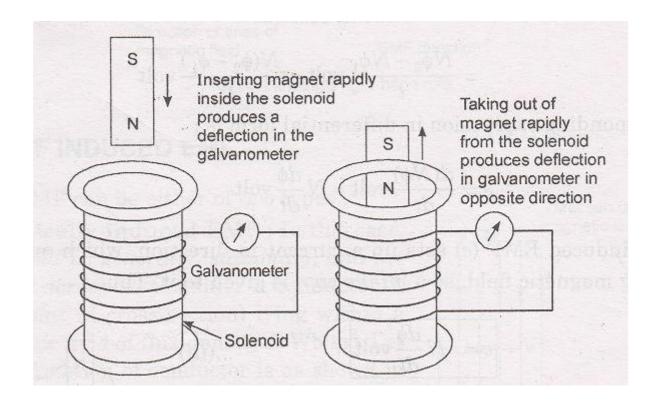
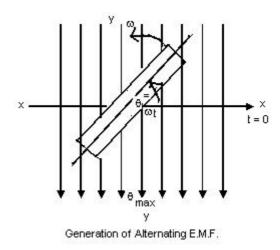


Illustration of electromagnetic induction.

For example, If we take a solenoid (i.e. a coil of a conducting material wound on a hollow cylinder of card board) and place it vertically on a table & connect the two ends of the coil to a sensitive galvanometer. Now, If we insert a magnet rapidly into the solenoid, a deflection in galvanometer needle is produced. Now, if we withdraw the magnet rapidly from the solenoid, a momentary deflection, but in opposite direction is produced. This demonstrates the fact that an electric current is induced in a circuit when the strength of magnetic field or the number of lines of force through it changes. The current so produced is called induced current & the emf causing this current to flow is called induced emf & this phenomena of production of induced emf as described above is called electro-magnetic induction.

Faraday's Laws of Electro-Magnetic Induction

- 1. Faraday's first law states that 'when the number of magnetic lines of force(or magnetic flux) passing through a circuit changes, an induced emf is set up in the circuit.
- 2. Faraday's second law states that the magnitude of emf induced is proportional to the rate of change of magnetic lines of force.



Suppose the flux of a coil having N turns, changes from initial value ϕ_1 weber to the final value of ϕ_2 weber in t seconds. Then , the initial flux linkage = [No. of Turns] x [initial flux linked with coil] = N ϕ_1

Similarly, the final flux linkage = [No. of Turns] x [final flux linked with coil] = N ϕ_2

Hence, the Induced EMF (e) = (Change in flux linkages/Time in seconds)

The corresponding expression in different form is $e=d(N\phi/dt)=Nd\phi/dt$ volts

Since the emf set up a current in direction which opposes the very cause producing magnetic field So a minus sign is given to it.

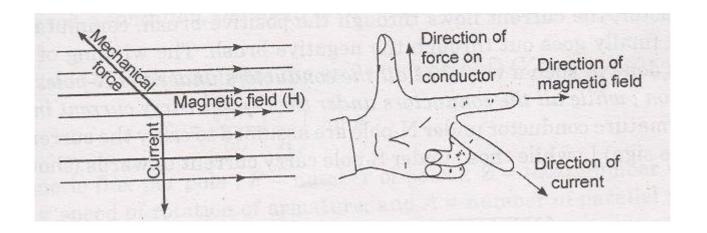
Thus $e = -N d\phi/dt \text{ volt}$

2. **LENZ's law**

Faraday's laws provide no idea regarding the direction of induced EMF. The direction of induced EMF is however, given by Lenz's Law which states that "the direction of the induced current(or EMF) is such that it opposes the very cause producing this current(or EMF)" i.e. it opposes the change in magnetic flux.

FLEMMING 's LEFT-HAND RULE

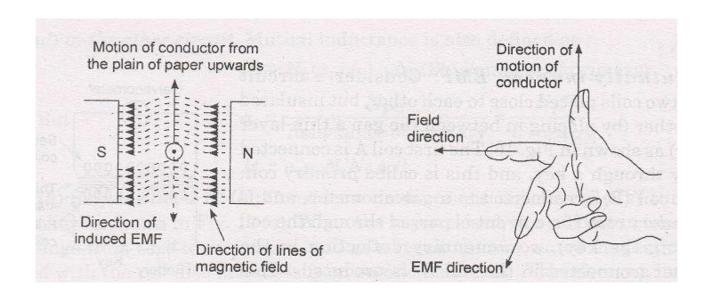
Flemming's left hand rule states that If we stretch out the thumb, the fore-finger & the middle finger of the left hand so that they are at right angles to each other then if the fore-finger points in the direction of magnetic field, the middle finger in the direction of current then the thumb points in the direction motion or the mechanical force experienced.



Direction of force experienced on a conductor carrying current, when placed in a magnetic field is given by Fleming's left-hand rule.

FLEMMING'S RIGHT-HAND RULE

Flemming's right hand rule states that If we stretch out the thumb, the fore-finger & the middle finger of the right hand so that they are at right angles to each other and if the fore-finger points in the direction of magnetic field, the thumb points in the direction motion of the conductor then the middle finger points in the direction of current.



Fleming's right-hand rule.

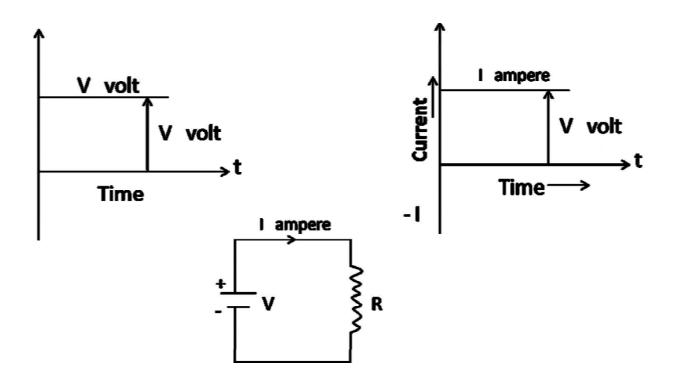
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CHAPTER-2

ALTERNATING CURRENT THEORY

what is D.C.

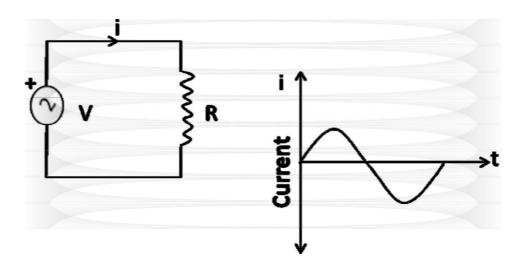
- 1. The Direct current or D.C. always flows in one direction & its magnitude remains unchanged
- 2. Here you see the voltage value is V volts & Current value is I amperes for all time to come i.e. as the time progresses.



[Figure (a)]

what is A.C

1. The Alternating current or A.C. is one which changes both in its direction & its magnitude.



[Figure(b)]

The AC current shown in the above circuit reverses it direction after some time as you see in the wave form diagram.

AC waveforms can also be other than like a sine wave that will be discussed later on. HOW A.C.

IS DIFFERENT FROM D.C

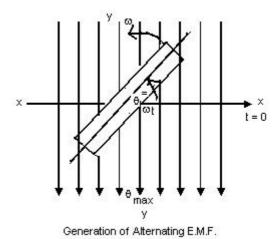
Alternating Current	Direct Current
1. The magnitude and direction both changes .	1.Both magnitude & Direction remain
2. By using transformers, A.C. voltages can be	constant.
increased or decreased as desired.	2. No such provision can be made.
3. A.C. circuit current can be decreased by using choke or capacitor without any appreciable power loss.	3. For decreasing D.C. circuit current, a resistance has to be used, whose power dissipation factor (I^2R) is large.
4. A.C. can be converted into D.C. by using a device, called convertor (rectification circuit)	4. D.C. can be converted to A.C. by using choppers (inverters).
5. A.C. cannot be used directly for electroplating, electrotyping, etc.	5. D.C. can be used directly for carrying out such operations.

Faradays laws of Electromagnetic Induction.

<u>First Law-</u> Whenever a coil cuts the magnetic lines of flux (ϕ) Electro-Magnetic Force(e.m.f) is induced in the coil i.e.

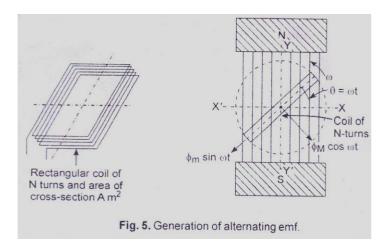
EMF Induced in a coil of N turns = $e=-N\ d\phi/dt$ Second Law- The magnitude of e.m.f induced is directly proportional to the rate of

change of Magnetic Flux cut by the coil i.e. $e=-N d\phi/dt$



GENERATION OF ALTERNATING EMF

Let there be a rectangular coil of N turns and is made free to rotate in a counter clockwise direction and is positioned inside the magnetic field produced by a north-south pole magnet as shown in the figure below.

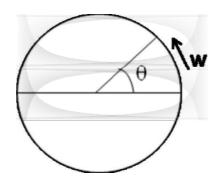


If the coil rotates at an angular velocity of ω radians per second then after a time of t seconds the coil will make an angle of θ = ω t degrees with the horizontal i.e. starting position.

Component of flux perpendicular to the plane of the coil is : -

Angle subtended by the coil in time t is

$$\theta = \omega t$$

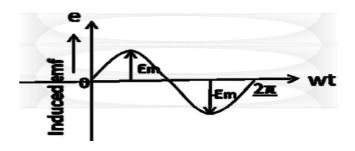


Magnetic Flux= \emptyset = \emptyset m Coswt For N turns N \emptyset

= N Øm Coswt

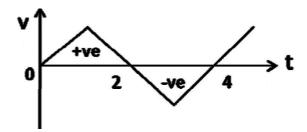
Induced emf in the coil according to Faradays Law = $e = -d(N\emptyset)/dt$ volt =- $d\{(N \emptyset m Coswt)\}/dt$ volts

= - NØm d (Coswt)/dt volts = ω NØm Sinwt volt e = Em Sinwt (Em = ω NØm)

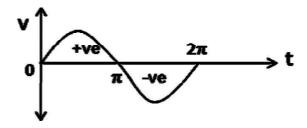


Questions/Answers

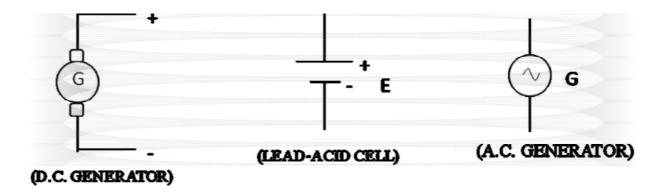
1. Is this wave forms AC?



2. What is the period of sinusoidal A.C. wave form shown below?

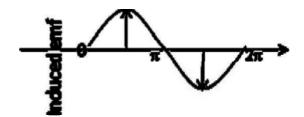


3. What is happening in a Generator or a Cell.



VARIOUS A.C. TERMS

AMPLITUDE: The maximum value (positive or negative) attained by an alternating quantity is called its Amplitude or Peak value.



CYCLE: One complete set of positive and negative values of an alternating quantity is known as cycle.

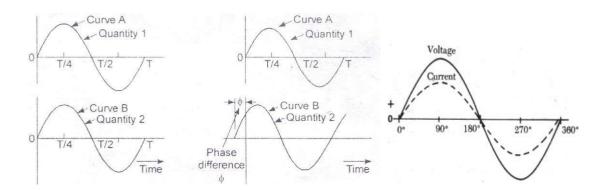
TIME PERIOD (T): The time period taken in seconds to complete one cycle of an alternating quantity is called its time period.

FREQUENCY (f): The number of cycles that occur in one second is called the frequency (f) of the alternating quantity.

ALTERNATION: Alternation is one-half of the cycle of an alternating quantity.

PHASE: Phase of an alternating quantity is the fraction of the time period or cycle that has elapsed since it last passed from the chosen zero position on origin.

PHASE DIFFERENCE: Phase difference between two alternating quantities is the fractional part of a period through which time of one alternating quantity has advanced over another alternating quantity.



INSTANTANEOUS VALUE: The value of an alternating quantity at any instant is called its instantaneous value.

AVERAGE VALUE

Average value of a.c. is that value of steady current (d.c.) which when flowing through a circuit transfers same amount of charge as is done by a.c. through the same circuit in same time.

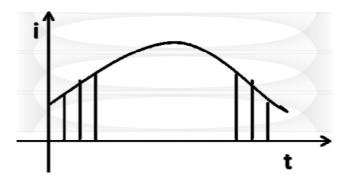
$$I_{av} = \frac{1}{T} \int_0^T i(t)dtor, \quad I_{av} = \frac{1}{2\pi} \int_0^{2\pi} id\theta$$

RMS / EFFECTIVE VALUE

The effective or r.m.s. value of an alternating current is that steady current (d.c.) which when flowing through a given resistance for a given time produces the same amount of heat as produced by the alternating current when flowing through the same resistance for the same time.

$$I \quad \underset{rms}{=} \quad \sqrt{\frac{1}{T} \int_{0}^{T} i^{2} d\overline{t}} \qquad \sqrt{\frac{1}{2\pi} \int_{0}^{2\pi} i^{2} d\theta}$$

Graphical Method



$$\frac{I}{rms} = \sqrt{\frac{i_1^2 + i_2^2 + \dots + i_n^2}{n}}$$

Amplitude factor (peak factor)

The ratio of peak value or maximum value to r.m.s. value of an a.c. quantity is called Amplitude factor.

$$Amplitude factor (peak factor) = \frac{Maximum \ value}{R.M.S. value}$$

Form factor:

The ratio of R.M.S. value to average value of an a.c. quantity is called form factor.

$$Form factor = \frac{R.M.S.value}{Average value}$$

Assignments / Discussion:-

- 1. Determine the following for the a.c. waveform given by $V = 141.4 \sin (628t)$
- a. Maximum value
- b. R.M.S. value
- c. Average value
- d. Amplitude factor
- e. Form factor
- f. Frequency
- g. Time period
- h. Determine the time taken to attain 100 volt after reaching maximum value and decreasing there after.

Solution

$$2\pi f = 628$$

 $100 = 141.4 \sin 628 t$

$$\sin 628t = (100/141.4) = (1/\sqrt{2}) = \sin 45, 135 = \sin (\pi/4), (3\pi/4)$$

Hence $628t = (3\pi/4)$ (Think why not $\pi/4$)

$$t = [3\pi/(4x628)] = ?$$

PHASOR REPRESENTATION OF ALTERNATING QUANTITY

A phasor is a vector rotating at a constant angular velocity in Counter-clockwise Direction.

At
$$t_1$$
, $e_1 = E_m \sin \omega t_1 = OA \sin \omega t_1$
At t_2 , $e_2 = E_m \sin \omega t_2 = OA \sin \omega t_2$
At t_3 , $e_3 = E_m \sin \omega t_3 = OA \sin \omega t_3$
At t_4 , $e_4 = E_m \sin \omega t_4 = OA \sin \omega t_4$
At t_5 , $e_5 = E_m \sin \omega t_5 = OA \sin \omega t_5$

and so on.

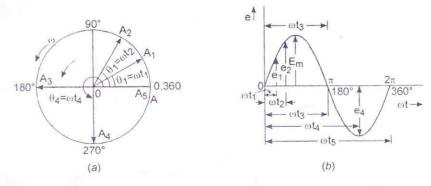


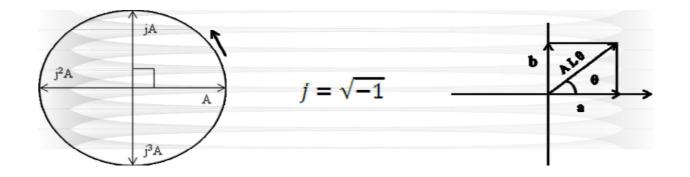
Fig. 7. Phasor (or vector) representation of alternating emf

Note: Instantaneous value of A.C. quantity is given by projection of rotating vector at that instant on vertical axis.

Phasor diagram is one in which different alternating quantities (sinusoidal) of the same frequency are represented by phasors with their correct phase relationship.

SIGNIFICANCE OF j- OPERATOR

Multiplication of a phasor with j rotates the phasor by an angle of $\pi/2$ or 90° in counter clock-wise direction.



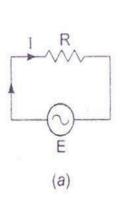
REPRESENTATION OF PHASOR IN COMPLEX PLANE

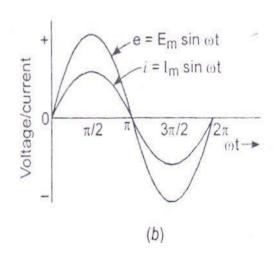
- I) Rectangular or Cartesian Form: A = a + jb, $\theta = tan^{-}(b/a)$
- II) Trigonometric Form (Euler's Identity): $A = Ae^{i\theta} = A (Cos \theta + jSin \theta)$
- III) Polar Form: $A = A \perp \theta$

Discussion:

- a. Convert 7+j24 to Polar coordinate? Modulus = $\sqrt{7^2 + 24^2}$ = 25, But Argument\Angle =?
- b. Convert $5/53.13^0$ to Rectangular coordinate $.[5(\cos 53.13^0 + j \sin 53.13^0)]$

A.C. THROUGH PURELY RESISTIVE CIRCUIT





Ohm's law states E = iR

E = Applied voltage

i = Instantaneous value of current R =

Ohmic resistance

Let us Find Current flowing in this circuit:

 $E = E_m Sin \theta = E_m Sin wt Also e = iR$

(Ohm's law)

 $iR = E_m Sin wt$

 $i = (\underline{E_m}/R) Sin wt = I_m Sin wt (Where <math>I_m = \underline{E_m}/R)$

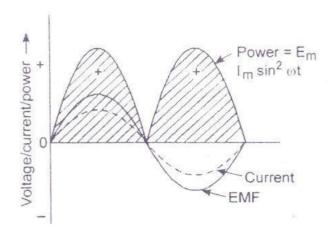
CONCLUSION: IN A PURELY RESISTIVE CIRCUIT THE APPLIED A.C. VOLTAGE & CIRCUIT CURRENT ARE IN-PHASE.

POWER IN A PURELY RESISTIVE CIRCUIT

 $P=ei=E_m \ . \ I_m \, Sin^2 \ wt = (E_m I_{\underline{m}} \underline{/2)} \, (1\text{-Cos } 2wt)$

CONCLUSION: AVERGE POWER DISSIPATION OVER COMPLETE CYCLE =

$$P = \frac{E_m I_m}{2} = \frac{E_m}{\sqrt{2}} \cdot \frac{I_m}{\sqrt{2}} = E_{rms} I_{rms}$$



Comparison of power wave with that of voltage, and current in a purely resistive circuit

Let us Solve

A voltage $v = 141 \text{ Sin } (314t + \pi/3)$ is applied to a resistance of 10 Ω . Find the R.M.S and maximum value of current

 $i = V/R = (141/10) Sin (314t + \pi/3)$

 $= 14.1 \text{Sin} (314t + \pi / 3)$

Maximum value =?

R.M.S value = Maximum value / $\sqrt{2}$ = ?

A.C. THROUGH PURELY INDUCTIVE CIRCUIT

Induced emf = $e_{in} = -L \frac{di}{dt}$

Applied voltage = e = L di / dt =

E_m Sin wt

 $di = (E_m/L)Sin wt.dt$

On integration

$$i=\,E_m\,/\,L\,\int$$
 Sin wt .
 $dt=E_m\,/\,wL$ (-Cos $wt)=\,(E_m\,/\,wL)$ Sin $(wt$ - $\pi\!/\,2)$
$$(where \;I_m=E_m\,/\,wL)$$

 $wL = 2 \pi fL = X_L = INDUCTIVE REACTANCE$



A.C. circuit with inductance only.

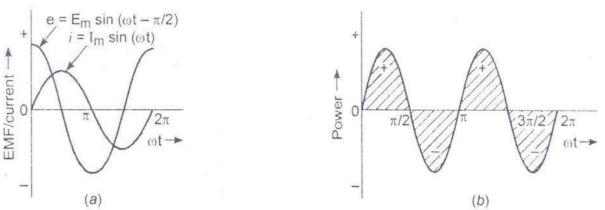
CONCLUSION:

IN A PURELY INDUCTIVE CIRCUIT THE CIRCUIT CURRENT (I) LAGS BEHIND THE APPLIED A.C. VOLTAGE (e) BY AN ANGLE OF π / 2 OR 90 0 .

POWER IN A PURELY INDUCTIVE CIRCUIT

$$\begin{split} p &= ei = E_m \;.\; I_m \, Sin \; wt \;.\; Sin \; (wt - \pi \,/\, 2) \\ \\ &= - \; E_m I_m \, Sin \; wt \;.\; Cos \; wt = \; - \; (E_m I_m \,/\, 2) \, Sin \, 2wt \end{split}$$

Power in complete cycle , P = - $(E_m I_m \, / \, 2) \int Sin \, 2wt = 0$



Graphs for A.C. circuit containing inductance only for: (a) voltage, and current; (b) power

CONCLUSION:

AVERGE POWER DISSIPATION BY A PURELY INDUCTIVE A.C. CIRCUIT IS ZERO.

Discussion/Assignment

A voltage V = 141 Sin (314t + π / 3) is applied to a inductance of 0.1 H. Find X_L , i , I_{MAX} Solution : $wL = 2~\pi~fL$

i.e., $X_L = INDUCTIVE REACTANCE = 314 \times 0.1 = WHAT$

$$i = V_m / X_L = Sin (314t + (\pi / 3) - (\pi / 2))$$

 $= 141 / 31.4 \sin (314t - \pi / 6)$

 $= 4.49 \text{ Sin } (314t - \pi / 6)$

Maximum value of current $I_{MAX} = FIND$

A.C. THROUGH PURELY CAPACITIVE CIRCUIT



A.C. through purely capacitive circuit

For a capacitor : C = q / v = q / e q = C.e

 $= C. E_m Sin \omega t$

(putting $e=E_m \sin \omega t$)

$$i = dq / dt = \frac{d(CE_m \sin \omega t)}{dt}$$

$$= \omega.C. E_m \cos \omega t$$

$$= \frac{E_m}{\sin \omega t} (wt + \pi / 2) = \frac{E_m}{K_c} (wt + \pi / 2)$$

$$\omega c$$

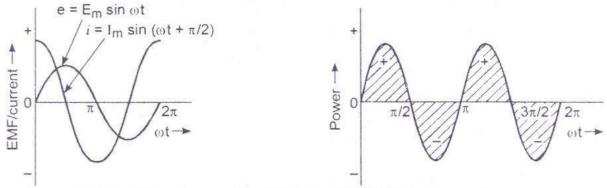
Where ,
$$Xc = \frac{1}{\omega c} = \frac{1}{2\pi \bar{f} c}$$
 Capacitive Reactance

CONCLUSION: IN A PURELY CAPACITIVE CIRCUIT THE CIRCUIT CURRENT (I) LEADS THE APPLIED VOLTAGE (e) BY AN ANGLE OF π / 2 OR $90^{0}.$

POWER IN A PURELY CAPACITIVE CIRCUIT

 $P = ei = E_m$. $I_m Sin wt$. $Sin (wt + \pi / 2)$

 $= E_m . I_m Sin wt . Cos wt = \frac{1}{2} . E_m I_m Sin 2wt$



Graphs of purely capacitive A.C. circuit for EMF, and current

CONCLUSION:

THE POWER DISSIPATION OVER A COMPLETE A.C. CYCLE IN A PURELY CAPACITIVE CIRCUIT IS ZERO.

Solve Yourself

A voltage $V = 141 \text{ Sin } (314t + \pi / 3)$ is applied to a 10 μf capacity. Find X_C , i, I_{rms} , I_{MAX} SOLUTION:

$$X_C = 1/wc = 1/314 \times 10 \times 10^{-6} = v318.47 \Omega$$

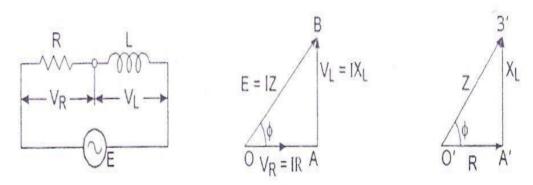
 $i = (141 / 318.47) \sin (314t + (\pi / 3) + (\pi / 2))$

 $= 0.443 \sin (314t + 5\pi / 6)$

Maximum value of current $I_{MAX} = 0.443$ Amp $I_{rms} =$

0.443 / 2 = 0.313 Amp

A.C. THROUGH SERIES R-L CIRCUIT



(a) R - L series A.C. circuit; (b) voltage triangle; (c) impedance triangle.

Voltage across resistance = V_R = IR

Voltage across Inductance = $V_L = IX_L$

Supply Voltage= E =
$$\sqrt{[V_R^2 + V_L^2]}$$

= $\sqrt{(IR)^2 + (IX_L)^2}$
= $I\sqrt{[R^2 + X^2]_L}$

$$I = E / \sqrt{[R^2 + X^2]}_L$$
$$= E / Z$$

Where , $Z = IMPEDANCE = \sqrt{[R^2 + X_L^2]}$

 $LZ = tan^{-}(X_L/R)$ CONCLUSION:

IN A SERIES R-L CIRCUIT CONNETED TO A.C. SUPPLY, THE APPLIED VOLTAGE (E) LEADS THE CIRCUIT CURRENT (I) BY AN ANGLE ϕ CALLED THE POWER FACTOR ANGLE.

POWER FACTOR IS COSINE OF THE ANGLE OF LEAD / LAG BETWEEN APPLIED VOLTAGE & CURRENT IN AN A.C. CURRENT.

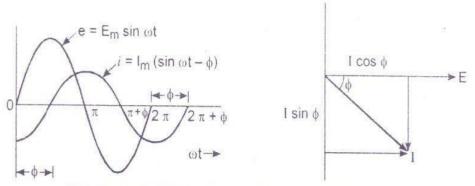
P.F. =
$$\cos \varphi = (R / Z)$$

$$P = V.I. Cos \phi = IZ.I.(R / Z) = I^2 R (ACTIVE POWER)$$

$$Q = V.I. Sin \phi = IZ.I.(X_L / Z) = I^2X_L (REACTIVE POWER) S = V.I$$

 $= IZ.I = I^2Z$ (APPARENT POWER)

$$S = \sqrt{(P^2 + Q^2)} \& LS = tan^{-}(Q/P)$$



Voltage, and current waves in R-L series A.C. circuit.

PROBLEM-

An inductive coil takes 10 Amp when connected to 250v, 50hz mains. The power consumed is 1000 watt. Find (a) Z, R, $X_L L$ (b) Power factor, (c) App power and reactive power (d) Phase angle between V & I.

SOLUTION:

(a)
$$Z = (V / I) = 250 / 10 = 25 \Omega$$

$$P = VI Cos \theta$$

$$\cos \theta = (P / VI) = (1000 / (250x10)) = 0.4$$

Sin θ 0.917

$$R = ZCos \theta = 25 \times 0.4 = 10 \Omega$$

$$X_L = Z \sin \theta = 25 \times 0.917 = 22.93 \Omega$$

$$L = (X_L / W) = (22.93 / (2 \pi x 50)) = 0.073 H$$

- (b) Power factor = $\cos \theta = 0.4$ lagging
- (c) App Power = S = VI = 2500 VA

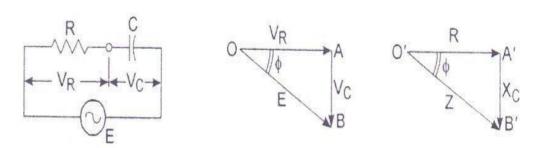
Reactive power = θ = VI Sin θ = 2500 x 0.917 = 2292.5 Vars

(d)
$$\cos \theta = 0.4$$

$$\theta = 66.42^{\circ}$$

Current phasor lags voltage phasor by 66.42⁰

A.C. THROUGH SERIES R-C CIRCUIT



(a) Series R-C A.C. circuit; (b) voltage triangle; (c) impedance triangle.

Voltage across resistance = V_R = IR Voltage across capacitance= V_c = IX $_c$

Supply voltage :=
$$E = \sqrt{V_R^2 + V_c^2}$$

$$=\sqrt{(IR)^2+(IX_C)^2}$$

=
$$I\sqrt{(R^2 + X_c^2)}$$

= IZ where $Z = \sqrt{(R^2 + X_c^2)} => I = E/Z$

$$Z = IMPEDANCE = \sqrt{[R^2 + X^2]}$$

$$LZ = tan^{-} (X_C / R)$$

CONCLUSION:

IN A SERIES R-C CIRCUIT CONNETED TO A.C. SUPPLY, THE APPLIED VOLTAGE (E) LAGS THE CIRCUIT CURRENT (I) BY AN ANGLE ϕ CALLED THE POWER FACTOR ANGLE.

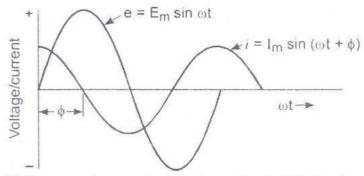
P.F. =
$$Cos \phi = (R / Z)$$

$$P = V.I. Cos \phi = IZ.I.(R / Z) = I^2 R (ACTIVE POWER)$$

$$Q = V.I. Sin \phi = IZ.I.(X_C / Z) = I^2X_C (REACTIVE POWER) S = V.I$$

$$= IZ.I = I^2Z$$
 (APPARENT POWER)

$$S = \sqrt{P^2 + Q^2} \& LS = tan^{-}(Q/P)$$



Voltage, and current waves in series R-C A.C. circuit.

PROBLEM-

A voltage V = V2 (230) Sinwt is applied to a series RC Circuit having R = 20Ω and C = $100 \mu F$.

Find (a) X_C , Z, (b) Y, B, G, (C) Current and power factor (d) S, P, Q (e) Write expression for instantaneous current.

SOLUTION: $V = 230 \perp 0^0$

(a)
$$X_C = (1 / wc) = (1 / 2 \pi x 50 x 100 x 100 x 10^{-6}) = 31.83 \Omega$$

$$Z$$
 = R - jX_C = $20-j31.83$ Ω = 37.59 \sqcup -57.86 Ω

(b)
$$Y = (1 / Z) = Admittance = (1 / 37.59 \bot -57.86 = 0.0266 \bot 57.86^{\circ}$$

$$= 0.01415 + j 0.0225$$
 Siemens $Y = G + jB$

So G = 0.01415 Siemens & B = 0.0225 Siemens

(c)
$$I = (V / Z) = (230L0^0 / 37.59 \bot -57.86^0 = 6.12 \bot 57.86^0 Amp$$

Power factor = $Cos(57.86^{\circ}) = 0.522$ leading

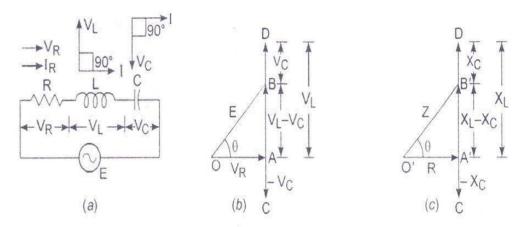
(d) App Power = $S = VI = 230 \times 6.12 = 1407.6 \text{ VA}$

Active power =
$$P = VI \cos \theta = (1407.6 \times 0.532) = 748.84$$
 watt

Reactive power = Q = - VI Sin
$$\theta$$
 = (-1407.6 x Sin 57.86⁰) = -1191.9 Vars

(e) Instantaneous value =
$$2 \times 6.12 \sin (wt + 57.86^{\circ}) = 8.65 \sin (wt + 57.86^{\circ})$$
 A.C.

THROUGH SERIES R-L-C CIRCUIT



(a) Series R-L-C A C circuit; (b) voltage triangle; (c) impedance triangle.

Voltage across resistance = $V_R = IR$ Voltage across

 $Inductance=V_L = IX_L \quad Voltage \quad across$

capacitance= $V_c = IX_c$

Supply Voltage=
$$E = \sqrt{[V_R^2 + (V_L - V_C)^2]} = \sqrt{[(IR)^2 + (IX_L - IX_C)^2]}$$

$$= I \sqrt{[R^2 + (X_L - X_C)^2]}$$

$$I = E / \sqrt{[R^2 + (X_L - X_C)^2]} = E / \sqrt{[R^2 + X^2]} = E / Z Z =$$

$$IMPEDANCE = \sqrt{[R^2 + (X_L - X_C)^2]}$$

$$LZ = tan^{-}(X_L - X_C) / R$$

CONCLUSION:

IN A SERIES R-L-C CIRCUIT CONNETED TO A.C. SUPPLY, THE APPLIED VOLTAGE (E) LEADS THE CIRCUIT CURRENT (I) IF $X_L > X_C$ & LAGS BEHIND CIRCUIT CURRENT IF $X_L < X_C$ & REMAIN IN-PHASE IF $X_L = X_C$.

$$P.F. = Cos \ \phi = (R \ / \ Z) = R \ / \ \ \sqrt{\{\ \ R^2 + (X_L \text{-} X_C)^2 \ }$$

$$P = V.I. Cos \phi = IZ.I.(R / Z) = I^2 R (ACTIVE POWER)$$

$$Q = V.I. \; Sin \; \phi = IZ.I. \; ((X_L \text{-} X_C) \; / \; Z) = I^2 \; [X_L \text{-} X_C] \; (REACTIVE \; POWER) \; \; S = V.I$$

 $= IZ.I = I^2Z$ (APPARENT POWER)

$$S = \sqrt{[P^2 + Q^2 \& LS = tan^-]}((X_L-X_C) / R)$$

PROBLEM-

A resistance of 10 Ω , inductance of 0.1 H & capacitance 50 micro farad are connected in series across a 230v, 50Hz supply. Find (a) X_L , X_C & Z, (b) I & Power factor (C) Active, reactive and apparent power (d) Y, G, B

SOLUTION: $V = 230 L 0^0$

(a)
$$wL = 2 \pi fL = X_L = INDUCTIVE REACTANCE 2 \pi fL$$

$$= 2 \pi 50 \times 0.1 = 31.41 \Omega$$

$$X_C = (1 / wc) = (1 / 2 \pi 50 \times 50 \times 10^{-6}) = 63.66 \Omega$$

$$Z = R + j (X_L - X_C) = 10 + j (31.41-63.66) = 10 - j32.25 = 33.76 \ L - 72.77^0$$

(b)
$$I = CURRENT = (V / Z) = (230 \bot 0^0 / 33.76 \bot -72.77^0 = 6.8 \bot 72.77^0 Amp$$

Power factor = $Cos(72.77^0) = 0.296$ leading

(c) App Power =
$$S = VI = 230 \times 6.8 = 1564 \text{ VA}$$

Active power =
$$P = VI \cos \theta = (1564 \times 0.296) = 462.9 \text{ watt}$$

Reactive power = Q = VI Sin
$$\theta$$
 = (1564 x Sin -72.77⁰) = -1496.80 Vars (d)

$$Y = (1 / Z) = Admittance = (1 / 33.76 \bot -72.77^0 = 0.0296 \bot 72.77^0$$

$$= 0.00877 + j 0.0283$$
 Siemens Y = G

$$+jB$$

So
$$G = 0.00877$$
 Siemens & $B = 0.0283$ Siemens

.....XXX.....

CHAPTER-3

BULK ELECTRIC POWER IS PRODUCED BY SPECIAL PLANTS KNOWN AS GENERATING STATIONS OR POWER PLANTS.

- 1. STEAM POWER STATION (THERMAL STATION)
- 2. HYDRO-ELECTRIC POWER STATION
- 3. NUCLEAR POWER STATION

STEAM POWER STATION (THERMAL STATION

CHOICE OF SITE

- 1. **SUPPLY OF FUEL**:- The steam power station should be located near coal mines so that transportation cost of fuel is minimum.
- 2. AVAILABILITY OF WATER:- A huge amount of water is required for the condenser for which it is it is essential that the plant should be located at the bank of a river or near a canal to ensure continuous supply of water.
- 3. TRANSPORTATION FACILITIES:- : A modern steam power station often requires the transportation of material and machinery. Therefore adequate transportation facilities by rail
- 4. COST AND TYPE OF LAND:- The steam power station should be located at a place where land is cheap and further extension if necessary is possible.
- 5. NEARNESS TO LOAD CENTRES:- In order to reduce transmission cost the plant should be located near the center of load.
- 6. DISTANCE FROM POPULATED AREA: As huge amount of coal is burnt in a steam power Plant due to which smoke and fumes pollutes the surrounding area. This necessitates that plant should be locate at a considerable distance from the populated areas.

MAIN UNITS OF PLANT

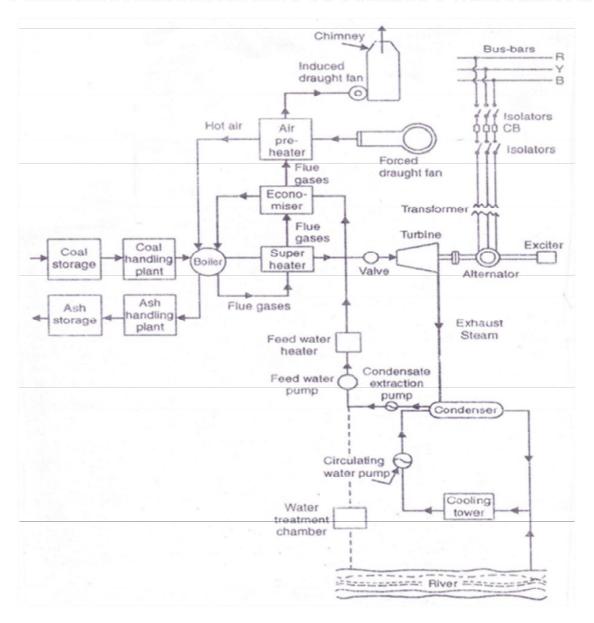
- 1. COAL STORAGE PLANT: Coal is transported to the power station by road or rail and is stored in coal storage plant.
- 2. COAL HANDLING PLANT:-: From the coal storage plant coal is delivered to the coal handling plant where it is pulverized for rapid combustion with out using excess amount of air.
- 3. ASH HAXIDLING PLANT:- The coal is burnt in the boiler & the ash produced after the complete combustion of coal is removed to the ash handling plant.
- 4. ASH STORAGE PLANT:- the ash from ash handling plant is then delivered to the ash storage plant for subsequent use as fertilizer etc.

- 5. BOILER:- The heat of combustion of coal in the boiler is utilized to convert water into steam at very high temperature and pressure. The flue gases from the boiler makes their journey through superheater, economizer, air pre-heater & are finally exhausted to the atmosphere through the chimney.
- 6. SUPERHEATER:- The steam produced in the boiler is wet and is passed through super heater where it is dried and super heated.
- 7. ECONOMISER:- An economizer is essentially a feed water heater & derives heat from the flue gases for the purpose.
- 8. AIR PREHEATER:- Air pre-heater increases the temperature of the air supplied for coal burning by deriving heat from flue gases.
- 9. FORCED DRAUGHT FAN: It draws air from atomosphere which is supplied to the boiler for effective combustion.
- 10. INDUCED DRAUGHT FAN: it draws the flue gas and sends to chimney.
- 11. CHIMNEY:- The hot flue gases go to the atmosphere though chimney.
- 12. **STEAM TURBINE**:- The dry and super heated steam from the super heater is fed to the steam turbine which converts the heat energy of steam tto mechanical energy.

13.

- 14. ALTERNATOR:- The alternator converts the mechanical energy of steam turbine to electrical energy.
- 15. CONDENSER: In order to improve the efficiency of the plant the steam exhausted from the turbine is condensed by means of a condenser. The condensate from the condenser is used as feed water to the boiler.
- 16. COOLING TOWER: The cooling tower provides a cooling arrangement for the feed water to be reused in boiler.

SCHEMATIC ARRANGEMENT OF STEAM POWER STATION



<u>Working of Thermal power Plant</u>: When the water from condenser is fed to the Boiler through Economiser it remains a little hot .The Boiler is a extremely heated chamber because of a continuous burning of Coal in presence of air injected by F.D fan through pre-heater.

So, the water gets converted to steam with very high temperature and pressure and reaches the Steam Turbine through Super-Heater. The Internal Energy of Steam gets converted to Mechanical Energy by Turbine and the Alternator converts the mechanical Energy of Turbine output to Electrical Energy. The Electrical Energy thus produced is supplied to the Bus-Bar for Power use.

Assignments / Discussion:-

➤ What are the Advantages / Disadvantages of a Steam Power Station ?

ADVANTAGES

- i) The Fuel (i.e. Coal) used is quite cheap.
- ii) Less initial cost as compared to other generating stations.
- iii) It can be installed at any place & the coal can be transported by Rail / Road.
- iv) It requires less space as compared to hydro-electric Power Station.

DISADVANTAGES

- i) It pollutes air / atmosphere due to smoke / fumes
- ii) Running cost is higher than hydro power plant.

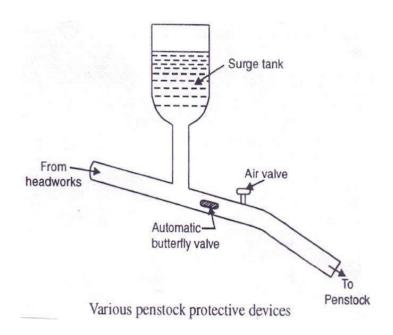
HYDRO-ELECTRIC POWER STATION

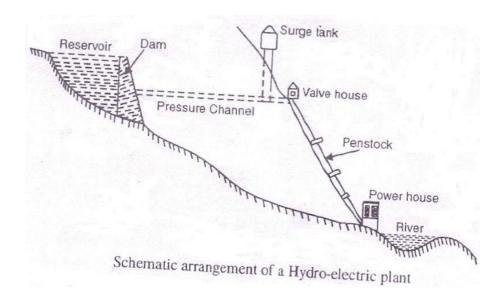
CHOICE OF SITE

- 1. AVAILABILITY OF WATER:- Since the primary requirement of a hydro-electric power station is the availability of huge quantity of water at a good head this requirement is very essential.
- 2. STORAGE OF WATER:-There are wide variations in water supply from a river or canal during the year. This makes it necessaryto store water by constructing a Dam in order to ensure the generation of power throughout the year.
- 3. COST & TYPE OF LAND: The land for the construction of Plant should be available at a reasonable price. Further the bearing capacity of the ground should be adequate to withstand the weight of heavy equipment to be installed.
- 4. TRANSPORTATION FACILITY: The site selected should be accessible by Rail and Road so that necessary equipment and machineries be easily transported.

MAIN CONSTITUENTS OF PLANT

- 1. DAM: A Dam is a barrier which stores water & creates water head. Dams are built of concrete or stone masonary, earth or rock fill.
- 2. SPILWAYS: There are times when the river flow exceeds the storage capacity of the reservoir. In order to discharge the surplus water from the storage reservoir into the river on the down-stream side of the dam, spill ways are used.
- 3. **HEAD WORKS**:-The head works consists of the diversion structures at the head of an intake. They generally include booms and racks for diverting floating debris, sluices for by-passing debris, sediments and valves for controlling the flow of water to the turbine.
- 4. SURGE TANK:-For close conduits abnormal pressure may cause damage to the conduit leading from head works to penstock. Surge tank acts as a protection for such situation.
- 5. PENSTOCKS:-Penstocks are open or close conduits which carry water to the turbines. They are generally made of reinforced concrete or steel.
- 6. **WATER TURBINES**:- Water turbines are used to convert the energy of falling water into mechanical energy.
- 7. **ALTERNATOR**: The alternator converts the mechanical energy of turbine to electrical energy.





Working of Hydro-Electric Power Plant: When the water from Reservoir is allowed to get released through pressure channel, it reaches the Valve house.

The surge tank is provided in order to safe guard the extra back-thrust of water causing heavy damage to Penstock. The valve house controls the amount of water that will flow to the power house turbines through the Large sized Pen-stocks.

Inside the power house the water Turbine convert the potential energy of water with sufficient head to Kinetic energy i.e. mechanical Energy which in turn acts as a prime-mover for the Alternator as before and generates Electrical Energy.

Assignments / Discussion:-

> State the Advantages / Disadvantages of a Hydro-Power Station?

ADVANTAGES

- i) It requires no fuel as water is used for the generation of Electrical Energy.
- ii) It is quite neat & clean as no smoke or ash is produced.
- iii) Running cost is very less as water is used.
- iv) It is simple in construction & requires less maintenance.
- v) It can be started quality as compared to Thermal Power Station.
- vi) In addition to generation of Electrical Energy these plants are also helpful in irrigation & control of floods.

DISADVANTAGES

- i) It involves high capital lost due to construction of dams.
- ii) Generation depends on average rainfall round the year.
- iii) High cost of transmission as these plants are located in hilly areas quite for off from localities.

NUCLEAR POWER STATION

CHOICE OF SITE

- 1.AVAILABILITY OF WATER: A huge amount of water is required for the condenser for which it is it is essential that the plant should be located at the bank of a river or near a canal to ensure continuous supply of water.
- 2. DISPOSAL OF WASTE: The waste produced by fission in a nuclear power station is generally radio-active which must be disposed off properly to avoid health hazards for which it must be buried in deep trench.
- 3. DISTANCE FROM POPULATED AREA:- The site for setting up a nuclear power station should be quite away from populated areas.
- 4. TRANSPORTATION FACILITY:- The site selected for a nuclear power station should have adequate facilities in order to transport the heavy equipment during erection.

NUCLEAR FUEL

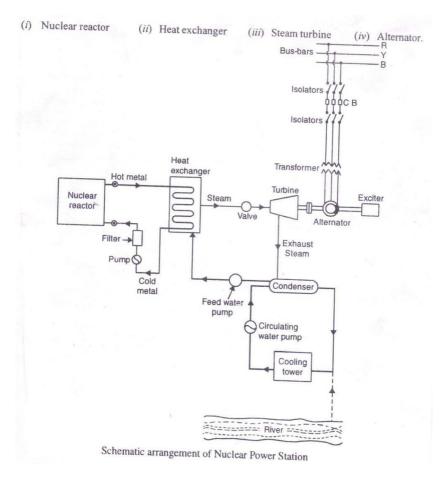
- 1. $URANIUM(U^{235})$
- 2. PLUTONIUM(Pu²³⁹)
- 3. THORIUM(Th^{232})

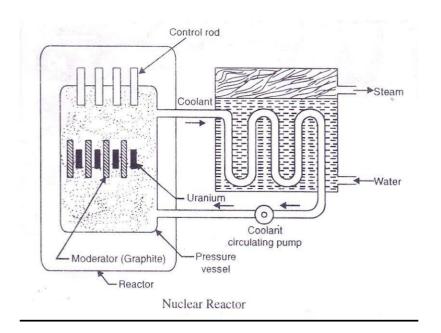
FISSION & CHAIN REACTION

When a U-235 atom is struck by a slow neutron, it will split into two or more fragments. This is called a nuclear fission. This splitting (fission) is accompanied by release of thermal energy in large quantity and two or three fast neutrons. These fast moving neutrons are slowed down by moderators so that they have high probability to hit other u- 235 atoms which in turn get fissioned and release heat and neutrons. This continuous self sustaining sequence of nuclear fissions is called CHAIN REACTION.

MAIN UNITS OF PLANT

- 1. NUCLEAR REACTOR: It is an apparatus in which the nuclear $fuel(U^{235})$ is subjected to nuclear fission.
- 2. HEAT EXCHANGER: The coolant gives up heat to the heat exchanger which is utilized in raising the steam & after giving up heat the coolant is again fed to the reactor.
- 3. STEAM TURBINE:- The dry and super heated steam from the super heater is fed to the steam turbine which converts the heat energy of steam to mechanical energy.
 - 4. ALTERNATOR:- The alternator converts the mechanical energy of turbine to E l e c t r c a l E n e r g y .





Working of Nuclear Power Plant: As discussed earlier, the chain reaction produces a huge amount of heat inside the Nuclear Reactor and requires a lot of care to control this reaction. The heat of the Reactor is carried to Heat-Exchanger by molten sodium which also heats the water injected into this Heat Exchanger chamber. After the water gets converted to steam with very high temperature and high pressure, the Turbine converts the internal Energy of steam to Mechanical Energy and this is converted to Electrical Energy by Alternator as before.

Assignments / Discussion:-

> State the Advantages / Disadvantages of a Nuclear Power Station?

ADVANTAGES

- i) There is saving in fuel transportation as amount of fuel required is less.
- ii) A Nuclear Power Plant requires less space as compared to other plants.
- iii) This type of plant is economical for producing bulk Electrical Energy.

DISADVANTAGES

- i) Fuel is expensive and difficult to recover.
- ii) Capital lost is higher than other plants.
- iii) Experienced workman ship is required for plant erection & commissioning.
- iv) The Fission by-products are radio active & can cause dangerous radio-active pollution. The disposal of by-product is big problem.

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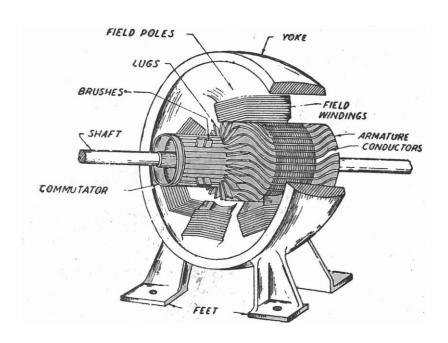
CHAPTER-4

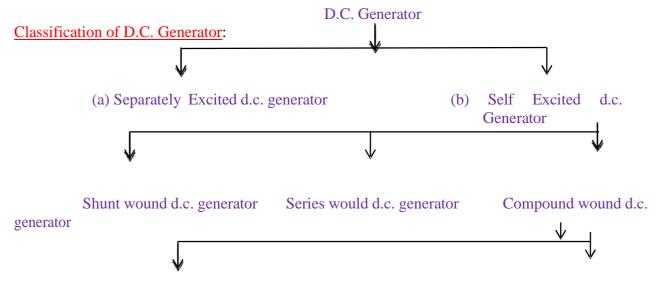
Introduction

A d.c. machine is a device which converts mechanical energy into electrical energy. When the device acts as a generator mechanical energy is converted into electrical energy. On the other hand when the device acts as a motor, the electrical energy is converted into mechanical energy. However, during the conversion process a part of the energy is converted into heat, which is lost and is not reversible. Thus an electrical machine can be made to work either as a generator or a motor.

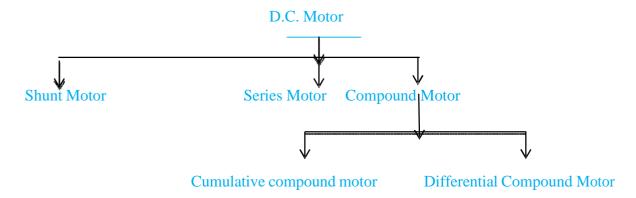
Main Parts of D.C. Machine

(1)Yoke or Magnetic frame (2) Pole Shoes and Pole Core (3) Armature Core (4)Field Coils (5) Armature windings (6)Commutator (7) Brushes and Bearings (8) Shaft (9) End Covers, (10)Feet.





Classification of D.C. Motor



4.8 <u>Uses of D.C. Generators :</u>

- (1) **Shunt Generator**
- (i) Lighting and Power Supply
- (ii) Charging batteries.
- (2) <u>Series Generator</u> –
- (i) Boosters.
- (3) <u>Compound Generator –</u>
- (i) Large range load
- (ii) Power Supply

Uses of D.C. Motors

- (1) Shunt Motor (i) Constant speed drive
- (ii) Drilling machine, lathes, elevators, water pump, cutting machine.
- (2) <u>Series Motor</u>
- (i) Electric Cranes
- (ii) Electric Trains
- (iii) Hoists
- (3) Compound Motor
- (i) Heavy tool machines
- (ii) Printing machines

Types of Single Phase Induction Motor

- (4) Split phase motor
- (5) Capacitor start motor
- (6) Capacitor start Capacitor run single phase Induction Motor.
- (7) Shaded Pole Motor -
- (8) Repulsion Motor

Uses:

(1) **Split phase motor**:

- (i) Small Pumps
- (ii) Grinders
- (2) <u>Capacitor start motor</u>
 - (i) Compressor
 - (ii) Pumps
- (3) <u>Capacitor start capacitor Run Motor</u>
 - (i) Compressor of Air-conditioner
 - (ii) Water Cooler
- (4) Shaded Pole Motor
 - (i) Small fans
- (5) Repulsion Motor
 - (i) Mixing Machine
 - (ii) Blowers

Types of Wiring:

Introduction

Electricity is used at home for different purposes such as light loads, fans, computer, refrigerator, cooler etc. In industries most of the machines run with electricity. The electric supply is given by the distribution company supplies upto energy meter of the consumer. The process by which the electric supply is made available to various load points through a network of conductors is called the wiring.

5.1 Types of Wiring

Different methods of wiring are used under different conditions. The selection of an individual system of wiring depends upon on the following factors.

- (i) Initial cost
- (ii) Durability
- (iii) Mechanical Protection
- (iv) Fire safety
- (v) Appearance
- (vi) Accessibility

(1) <u>Cleat Wiring</u>

Single core VIR (Vulcarized India Rubber) or PVC (Poly Vinyl Chloride) cables are used in this

wiring. The cables are run in grooves of glazed porcelain cleats which are fastened in wooden plugs (gutties) mounted on walls.

Taking the above factors into account, any of the following types of wining are used :-

- (i) Cleat wiring
- (ii) Wooden casing and capping wiring
- (iii) CTS or TRS wiring
- (iv) Lead sheathed wiring
- (v) Conduit Pipe Wiring

Merit

- (i) It is cheapest system of wiring.
- (ii) A little skill is required to lay the wining.
- (iii) The wiring can be dismantled easily and used again with very little waste of material.

Demerit

- (i) There is no protection from mechanical injury, fire, gas or water.
 - (ii) It is rarely employed for permanent jobs.
 - (iii) It is not good looking.

2. Wooden casing and capping wiring

The casing is base which consists of wooden block of seasoned teak wood and has usually tow grooves to accommodate wires. The casing is fixed on the wall with the help of screws and gutties. After placing the wires in the grooves casing at the top is covered by means of rectangular strips of seasoned wood of same width known as capping with the help of screws.

Merits:

- (i) It gives better appearance then cleat wiring.
- (ii) There is sufficient mechanical and environmental protection to the wires/ cables used.
- (iii) Easy to inspect only by opening the capping.
- (iv) Easy to install and rewire.

Demerits

- (i) Costlier in compare to cleat wiring.
- (ii) There is risk of fire.
- (iii) It is not suitable for damp situation.

3. <u>C.T.S. or T.R.S. wiring</u>

In this system of wiring generally C.T.S. (cable Tyre Sheath) or T.R.S. (Tough Rubber Sheathed)

conductors are employed. The conductors are run on well seasoned perfectly straight and well varnished teak wood batten of different width. The width of the batten is chosen depending upon the number of wires to be run on it.

Merits

- (i) It is easy to install and repair.
- (ii) It gives nice appearance.
- (iii) This type of wiring gives sufficient mechanical protection to the cable.

Demerits

- (i) The conductors are upon and liable to mechanical injury, can not be used in workshop.
- (ii) It takes more time for installation.
- (iii) The fire risk is high.
- (iv) Its performance is affected under damp condition.

4. <u>Lead Sheathed Wiring</u>

This system of wiring is similar to CTS or TRS wiring. Only difference is that in this case VIR conductors covered with lead alloy sheath (metal sheathed cable) are used. The lead sheathed cables are run on the Wooden battens.

<u>Merits</u>

- (i) The conductors are protected against mechanical injury.
- (ii) It is free from fire hazards.
- (iii) It can be installed in open space.
- (iv) It has longer life.

Demerits

- (i) It is relatively expensive due to the cost of lead sheath.
- (ii) In case of leakage, there is every risk of shock.
- (iii) Skilled labour and proper supervision is required. Other wise, the durability of insulation may be affected.

5. Conduit wiring

There are two types of conduit wiring

- (i) Surface conduit wiring
- (ii) Concealed conduit wiring

In surface conduit wiring the conduit run over the wall supported by means of saddles where as in concealed conduit wiring the conduit is embedded in the walls and ceilings by placing in the premade cavity in them.

Merits

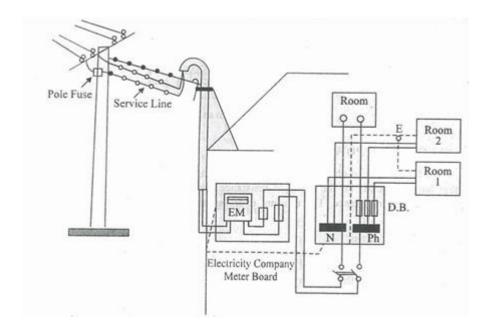
- i. The wiring presents a neat and attractive appearance.
- ii. It gives good protection against fire, mechanical damage & moisture.

iii. Its durability is very high.

Demerits

- i. It is costly system of wiring.
- ii. Highly skilled technician is necessary.
- iii. It requires more time for erection.

5.2 Layout of House hold Electrical Wiring (Single Line Diagram)



5.3

5.4 Basic protective Devices used in House hold wiring:

- 1. Fuse 2. MCB (Miniature Circuit Breaker)
- 3. Lightening arrester 4. Earthing Wire

5.5 <u>Electrical Power</u>

As we have learnt that power consumed by load depends on the value of resistance, current through the resistance and voltage across the resistance.

$$P = VI$$

 $\Rightarrow P = V^2/R \Rightarrow P = I^2R$

Thus, I watt is the power consumed by resistive load when current is 1A and Voltage Across is 1V

1 Killowatt (KW) = 1000 W 1 HP (Horse Power) = 746 W

Ex. A heater takes 8A current at 250V supply. Calculate how much power does it consume ?

Solution: Given I = 8A, V = 250V

P = V, I = 250 X 8 = 2000W = 2KW

5.6 Power in small Electrical Installation

Ex. A building has the following electrical appliances (i) 1 KW Motor. (ii) 2 bulbs 100w rating each (iii) Two fans having 60w each (iv) one heater 1.5 KW. Calculate the total Power Consumed by the building if all loads are switched on.

Solution: Total Power (P) = Sum of individual Power of all appliances. $P = P_1$

 $+ P_2 + P_3 + P_4$

 $P = 1000 + (2 \times 100) + (2 \times 60) + 1500$

P = 1000 + 200 + 120 + 1500 P = 2820

W = 2.82 KW

5.7 **Electrical Energy** Energy =

Power X Time => E = P X t

The unit of energy will depend upon the unit of Power and unit of time. When

P = 1 watt, t = 1 Second

Energy (E) = 1 W X 1S = 1 Watt Second = 1 Joule When P

= 1 Watt, t = 1 hour

Energy = 1 Watt X 1 hour = 1 Watt. hour 1 watt.

hour = 1 watt X (60 X 60) Second

1 watt hour = $3600 \text{ Watt Second} = 3600 \text{ J} = 3.6 \text{ X } 10^3 \text{ Joules}$

Similarly for bigger unit 1 Kwhr = 1000 whr.

So 1 Kwhr = $1000 \times 3600 = 3.6 \times 10^6 \text{ Joules}$

1 Kwh is called 1 Unit

Ex. A building has the following electrical appliances (i) A 1 HP motor running for 5 hrs. in a day. (ii) Three fans each of 80W running for 10 hrs. in a day. (iii) Four tube lights of 40W running for 15 hrs. per day. Find the monthly bill for the month of November if unit cost of bill is Rs.2.50.

Solution (i) Electrical Energy Consumed per day for motor = $746 \times 5 = 3730 \text{ whr} = 3.730 \text{ kwhr}$.

(ii) Electrical Energy Consumed per day by three fans = $3 \times 80 \times 10 = 2400 \text{ whr} = 2.4 \text{ Kwhr}$.

(iii) Electrical Energy Consumed per day by four tube lights = $4 \times 40 \times 15 = 2400$ whr = $2.4 \times 15 = 2400$ whr.

Total Energy Consumed = 3.73 + 2.4 + 2.4 = 8.53 Kwhr = 8.53 units.

In the month of November total Electrical Energy Consumed $= 8.53 \times 30 = 255.9 \text{ units}$. Monthly bill $= 255.9 \times Rs.2.5 = Rs.639.75P$.

5.8 Earthing

The process of connecting metallic bodies of all the electrical apparatus and equipment to the huge mass of earth by a wire having negligible resistance is called earthing.

Necessity of Earthing

- (i) To prevent electrical shock to the human being if the electrical appliance (body) are charged.
- (ii) To prevent risk of fire due to leakage current through un wanted path.
- (iii) To protect large building and machines from lightning by connecting lightning arrester to the general mass of the earth.

Measurement and Measuring Insteruments

7.1 Introduction:

Tests and measurements are important in designing, evaluating, maintaining and servicing electrical circuits and equipment. In order to detect electrical quantities such as current ,voltage, resistance or power ,it is necessary to transform an electrical quantity or condition into a visible indication. This is done with the aid of instruments (or meters) that indicate the magnitude of quantities either by the position of a pointer moving over a graduated scale (called an analogue instrument) or in the form of a decimal number (called a digital instrument).

Measuring instruments are classified according to both the quantity measured by the instrument and the principle of operation. Three general principles of operation are available:

(i) Electromagnetic, which utilizes the magnetic effects of electric current; (ii)Electrostatic; which utilizes the forces between electrically –charged conductors; (iii)Electro-thermic , which utilizes the heating effect.

Electric measuring instruments and meters are used to indicate directly the value of current, voltage, power or energy. In this lesson, we will consider an electromechanical meter (input is as an electrical signal results mechanical force or torque as an output) that can be connected with additional suitable components in order to act as an ammeters and a voltmeter. The most common analogue instrument or meter is the permanent magnet moving coil instrument and it is used for measuring a dc current or voltage of an electric circuit.

On the other hand, the indications of alternating current ammeters and voltmeters must represent the RMS values of current, or voltage, respectively, applied to the instrument.

Electrical measuring instruments used to measure electrical quantities such as current, voltage, power ,energy& frequency etc.

There are different types of measuring instruments such as

Ammeter measure current, voltmeter measure voltage, Wattmeter measure power, Energy meter measure energy and Ballistic Galvanometer measure charge.

Instruments are divided into two types such as

- (i) Primary instruments/Absolute instruments
- (ii) Secondary instruments

(i) Primary instruments/Absolute instruments:

These instruments give the magnitude of the quantity under measurement in terms of physical constants of the instrument. Example Tangent Galvanometer and Rayleigh's current balance.

These instruments are not generally used. These instruments are used in International Laboratory for testing or calibrating.

(ii) **Secondary Instruments**:

These instruments are calibrated by comparisons with an absolute instrument or secondary instrument which has already been calibrated against an absolute instrument. Example:voltmeter, ammeter etc.

These types of instrument are used in various laboratories for experimental purposes.

Secondary instruments are divided into following types such as

(a)Indicating Instruments

(b)Recording Instruments

(c)Integrating Instruments

(a)Indicating Instruments:

Indicating instruments are those which indicate by movement of a pointer over a calibrated scale, the r.m.s value of the electrical quantity under measurement at the time of measurement. For example, voltmeter, ammeter, wattmeter etc. This is shown in Fig. 7.1(a)&(b).

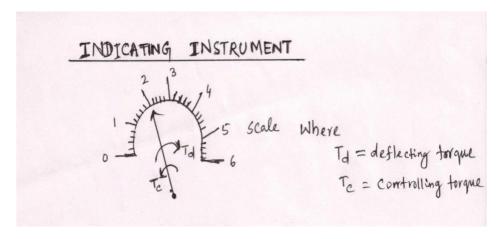


Figure: 7.1(a) Indicating Instrument.

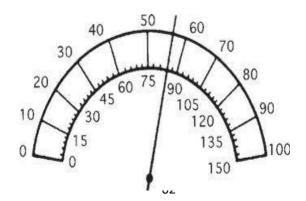


Figure: 7.1(b)Indicating

(b) Recording Instruments:

Recording instruments are those which gives a continuous record of the variation of some electrical quantity (such as current, voltage or power) with respect to time.

A pen attached to the moving system traces a graph on a sheet of paper by revolving drum. Example , a recording wattmeter gives daily and annual load curves. This is shown in Fig.7.1(c).

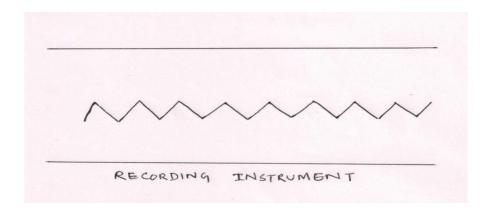


Figure: 7.1(c)Recording Instrument

(c) Integrating Instruments:

These types of instrument register the amount of energy or quantity of electricity supplied to a circuit over a period of time. Example: Watt-hour meter, Ampere-hour meter.

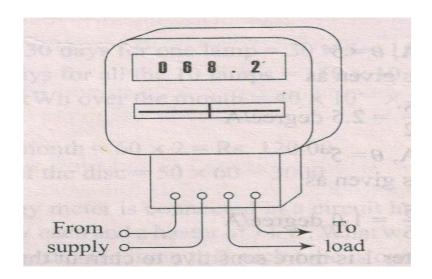


Figure: 7.1(d)Integrating Instrument

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For operation of an indicating instrument three kinds of torques are required.

These are namely

- (a) Deflecting torque
- (b) Control torque
- (c) Damping torque
- (a) Deflecting Torque or (Operating torque)(T_d):

Deflecting torque is an important torque in an indicating instrument which makes the pointer to deflect. Without deflecting torque the pointer will always free at zero.

(b) Control torque or Restoring torque (T_c):

This torque control the movement of the pointer and stop the pointer at required place. Without control torque the pointer will always reach at final position.

Controlling torque opposes the deflecting torque.

(c) Damping torque (T_d) :

Without damping torque the pointer makes oscillation about the steady state position. This oscillations are damped out by means of damping torque.

Damping torque present only when the pointer moves and becomes zero when the pointer is at steady state position.

There are two types of controlling torque

- (i) Gravity control method
- (ii) Spring control method

USES OF PMMC TYPE INSTRUMENTS:

A Multi-range Ammeters and Voltmeters:-

An ammeter is required to measure the current in a circuit and it therefore connected in series with the components carrying the current. If the ammeter resistance is not very much smaller than the load resistance, the load current can be substantially altered by the inclusion of the ammeter in the circuit.

To operate a moving coil instrument around a current level in 50 milliamper range is impractical owing to the bulk and weight of the coil that would be required. So, it is necessary to extend the meter-range shunts (in case of ammeters) and multimeters (in case of voltmeters) are used.

For higher range ammeters a low resistance made up manganin (low temperature coefficient of resistance) is connected in parallel to the moving coil as shown in Fig.7.4 and instrument may be calibrated to read directly to the total current

APPLICATIONS:--

- (1) PMMC IS USED AS AN AMMETER
- (a) For low current range:--

Current is responsible for deflection for few milliammeter used.

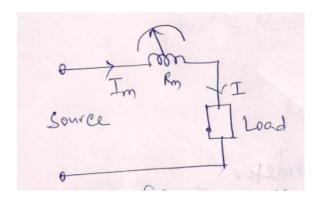


Fig.7.7(a) PMMC with low current rating

(2) PMMC USED AS VOLTMETER :--

When PMMC is used as oltmeter, a resistance is connected in series with the voltmeter called multiplier.

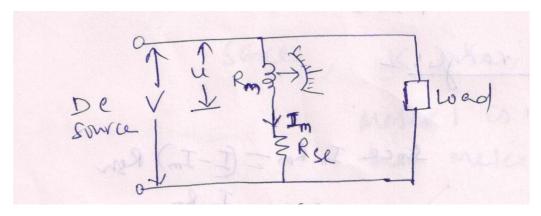


Fig.7.7(b) PMMC as Volt meter.

Advantages of PMMC Type Instrument:--

- (i) Scale is uniform.
- (ii) power consumption.
- (iii) It has high torque/weight ratio.
- (iv) Accuracy is very high.
- (v) Damping is effective.
- (vi) It can be used for multiple range of current and voltage.
- (vii) It has no hysteresis error.
- (viii) It does not have stray magnetic field error.
- (ix) It can be used in any position.

Disadvantages:-

- (i) It can measure only DC.
- (ii) It is a delicate instrument.
- (iii) It is costly.
- (iv) Aging problem due to permanent magnet.

Application:-

- (i)To measure voltage.
- (ii) To measure current.
- (iii) It is used in DC Galvanometer.
- (iv) It is used in Ballistic Galvanometer to measure charge.

Ammeter

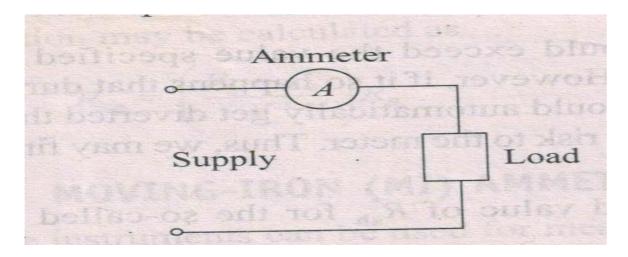
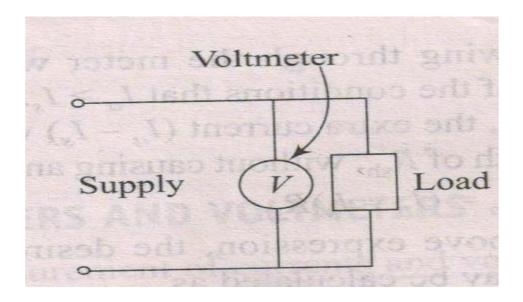


Fig. 7.5.3(a) Ammeter connection

Ammeter Design: While designing the PMMC instruments to be used as ammeters the coil should have the least resistance(thick coils with less turns) such that the instrument being connected in series with the load does not affect the load current much.

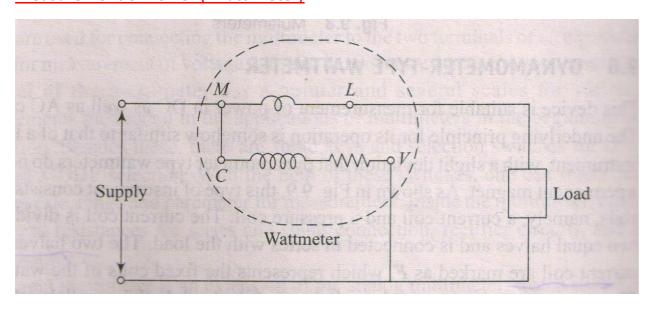
Voltmeter



Voltmeter design:

PMMC instruments meant to be used as voltmeters should have coils with very high value of resistance (thin coils with more turns) such that it becomes capable to sustain the pressure of the applied potential and takes a current as small as possible without effecting much of the load current when connected parallel across load. So Voltmeter should be connected in parallel to the load.

Measurement of Power (Watt meter)



Dynamometer type wattmeters are suitable for mesuement of power in DC as well as AC circuits.